

# PB SERIES

# POWDER BRAKE DYNAMOMETERS

Magtrol offers 3 types of dynamometer brakes to absorb load: Hysteresis (**HD Series**), Eddy-Current (**WB Series**) and Magnetic Powder (**PB Series**). Each type of Dynamometer has advantages and limitations and choosing the correct one will depend largely on the type of testing to be performed. With over 50 standard models to choose from, Magtrol Sales professionals are readily available to assist in selecting the proper Dynamometer to meet your testing needs.

#### FEATURES \_\_\_\_\_

- 12 Models with Maximum Torque 600 mN·m ... 1 200 N·m (84 oz·in ... 885 lb·ft)
- Braking Power: 150 W ... 48 kW
- Stable Braking Torque
- Low Moment of Inertia
- Operation in Either Rotational Direction
- Braking Torque Measurement Integrated
- Integrated Optical Speed Sensor
- Special designs available upon request



Fig. 1: 1PB 115 | Eddy-Current Dynamometer

#### DESCRIPTION \_\_\_\_

Powder Brake Dynamometers (PB Series) are ideal for applications operating in the low to middle speed range or when operating in the middle to high torque range. Powder Brakes provide full torque at zero speed and are water-cooled, allowing for power ratings up to 48 kW. PB Series Powder Dynamometers integrate a torque measuring system with an accuracy ratings  $\pm 0.3\%...\pm 0.5\%$  full scale, depending on size and system configuration.

#### APPLICATIONS \_\_\_

Mounted on test benches, the PB Series Powder Dynamometers allow performance and reliability testing on driving elements such as servomotors, geared motor, gearbox, windshield wiper motor, starter motor, fans, drills, hydraulic transmission systems and motors for domestic appliances.

#### POWDER DYNAMOMETER OPERATING PRINCIPLES \_\_\_\_\_

The PB Series - Powder Dynamometers contain, as their name suggests, a magnetic powder. The electrical current passing through the coil generates a magnetic field, which changes the property of the powder, thus producing a smooth braking torque through friction between rotor and stator. The Powder Dynamometers (PB) produce their rated torque at zero speed. The element to be tested can be loaded at standstill to determine the starting torque.

# **OPTICAL SPEED SENSOR**

Each PB Series Dynamometer has an optical speed sensor delivered as standard. PB 2.7 & PB 43 has an optical speed sensor with a 30 PPR (Pulses Per Revolution); PB 65, PB 115 & PB 15 has an optical speed sensor with a 60 PPR.

For higher speed resolution in low speed applications, Magtrol offers a 600 PPR or 6000 PPR encoder as an option.



# DYNAMOMETER CONFIGURATIONS \_

The Dynamometers can be complemented by various electronic modules such as the DES Series (Power Supply), TSC 401 (Torque/Speed Conditioner) and DSP 7000 (High Speed Programmable Dynamometer Controller).

Magtrol also offers In-Line Torque Transducers (TS Series or TM Series) or Torque Flange (TF Series) for extremely

accurate torque and speed measurement. For a dynamic, high-precision system, the torque transducer can be mounted in line between the unit under test and the dynamometer, providing a torque accuracy of 0.1%.

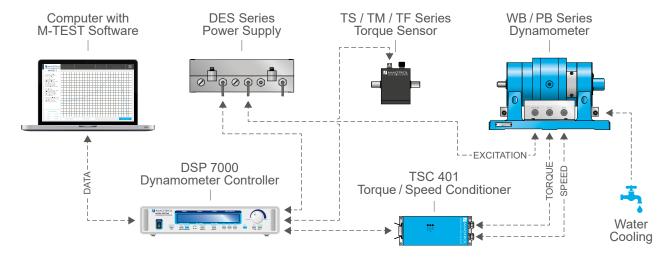


Fig. 2: Configuration of the PB Series Dynamometer with its accessories

#### SPECIFICATIONS.

NOTE: For continuous operating (≥ 2 hours) at constant torque or power, please consider 20% reserve in both torque & power

MODEL	RATED 1	FORQUE	DRAG T DE-ENE		ZED NOMINAL INPUT INER		RATED POWER	RATED SPEED a)	MAX. SPEED	EXCITATION CURRENT
	N⋅m	oz∙in	mN⋅m	oz∙in	kg·m²	lb·ft·s²	W	rpm	rpm	Α
1PB2.7	0.6	84	18	2.54	1.49×10 <sup>-5</sup>	1.09 × 10 <sup>-5</sup>	150			0.5 b)
2PB2.7	1.2	169	30	4.24	2.33×10 <sup>-5</sup>	1.71×10 <sup>-5</sup>	300	2390	10000	1.0 b)
4PB2.7	2.4	339	48	6.79	$4.03 \times 10^{-5}$	2.97 × 10 <sup>-5</sup>	600			2.0 b)
1PB43	5.0	708	100	14.10	1.41 × 10 <sup>-4</sup>	1.03 × 10 <sup>-4</sup>	500	OFF	4000	1.0 b)
2PB43	10.0	1416	200	28.30	2.40 × 10 <sup>-4</sup>	1.77 × 10 <sup>-4</sup>	1000	955	4000	2.0 b)
MODEL	RATED 1	FORQUE	DRAG T DE-ENE		NOMINAL IN	PUT INERTIA	RATED POWER			EXCITATION CURRENT
	N⋅m	lb·ft	N·m	lb∙in	kg·m²	lb·ft·s²	kW	rpm	rpm	A
1PB65	25	18.4	0.5	4.42	0.92×10 <sup>-3</sup>	6.78×10 <sup>-4</sup>	1.5	570	3000	2.5 <sup>c)</sup>
2PB65	50	36.8	1.0	8.85	1.71 × 10 <sup>-3</sup>	1.26 × 10 <sup>-3</sup>	3.0	570	3000	5.0 <sup>c)</sup>
1PB115	100	73.7	2.0	17.70	1.24 × 10 <sup>-2</sup>	9.14×10 <sup>-3</sup>	5.0	400	2000	2.5 <sup>c)</sup>
2PB115	200	147.5	4.0	35.40	$2.50 \times 10^{-2}$	1.84 × 10 <sup>-2</sup>	10.0	480	3000	5.0 <sup>c)</sup>
1PB15	300	221.0	6.0	53.10	5.40 × 10 <sup>-2</sup>	3.98 × 10 <sup>-2</sup>	12.0			4.0 d)
2PB15	600	442.0	12.0	106.20	1.08 × 10 <sup>-1</sup>	7.96×10 <sup>-2</sup>	24.0	382	2000	7.5 <sup>d)</sup>
4PB15	1200	885.0	24.0	212.41	2.16 × 10 <sup>-1</sup>	1.59 × 10 <sup>-1</sup>	48.0			12.0 <sup>d)</sup>

a) Depending on torsionnal stifness of the drive line, magnetic powder may generate a "slip-stick" effect (torsional vibration) at low speed (around 10 rpm)

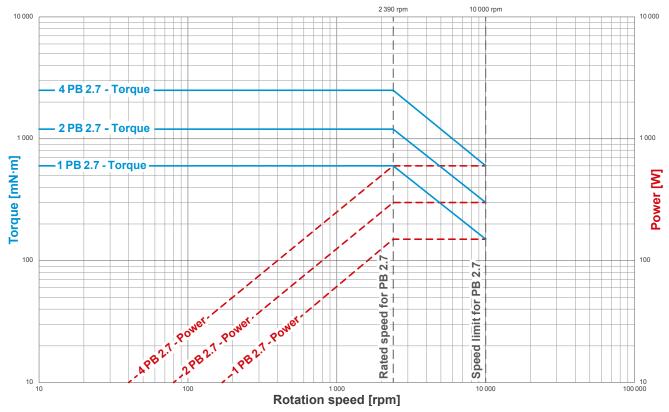
b) Voltage @ 20 °C : 24 V

c) Voltage @ 20°C: 30 V

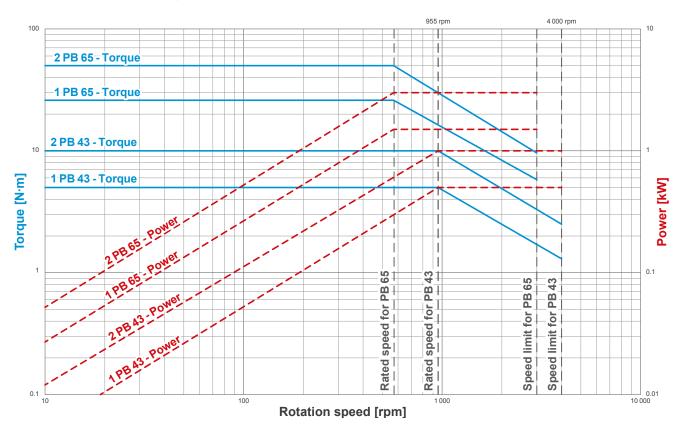
d) Voltage @ 20 °C : 45 V



# PB 2.7 TORQUE-SPEED-POWER CURVES \_

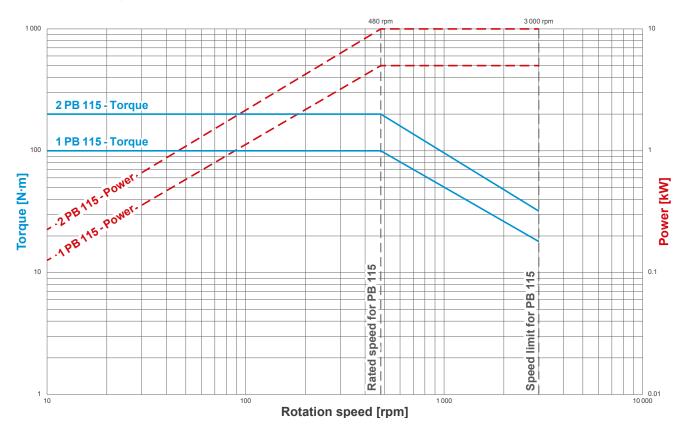


# PB 43 & PB 65 TORQUE-SPEED-POWER CURVES \_

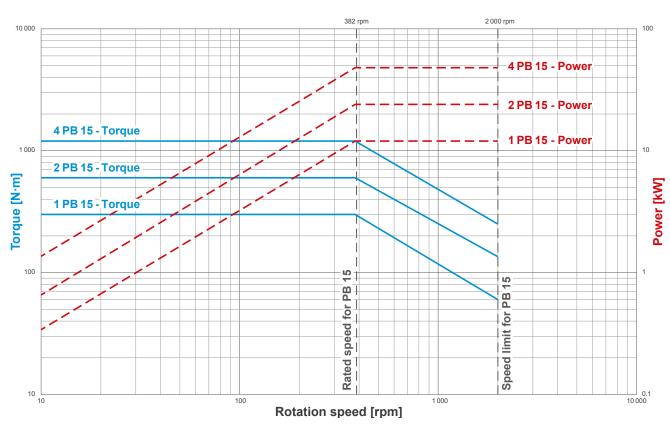




# PB 115 TORQUE-SPEED-POWER CURVES \_

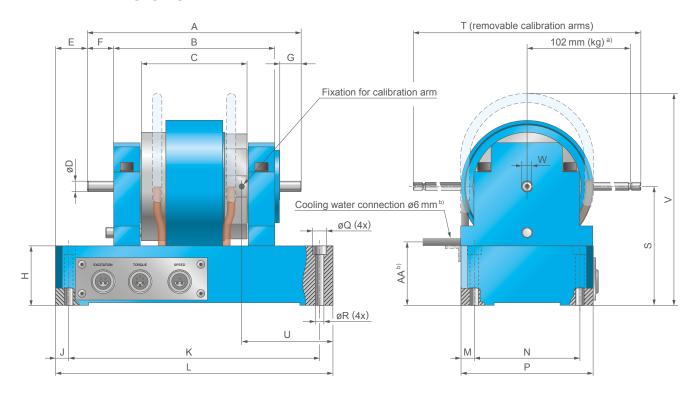


# PB 15 TORQUE-SPEED-POWER CURVES \_





# PB 2.7 DIMENSIONS



**CAUTION**: All PB Series Dynamometers must be water cooled.

NOTE: Original dimensions are in metric units. Dimensions converted to Emgéish units have been rounded up to 4 decimal places.

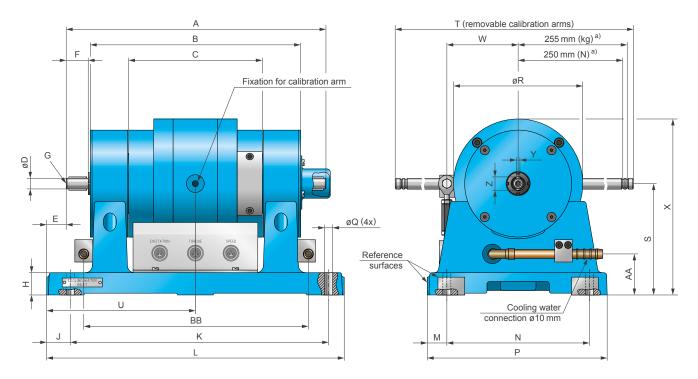
NOTE: Original dime	ensions a	are in me	etric uriits	s. Dimen	SIONS COL	iverted t	o Emger	SII UIIIIS	nave bee	en round	ed up to	4 decim	ai piaces	-
MODEL	units	Α	В	С	øD	Е	F	G	Н	J	K	L	M	N
4 BB 0 7	mm	138	98	56	8h5	36	20	16	45	10	190	210	10	80
1PB-2.7	in	5.43	3.86	2.2	0.3148 0.3149	1.42	0.79	0.63	1.77	0.39	7.48	8.27	0.39	3.15
0.00.0	mm	162	122	80	8h5	24	20	16	45	10	190	210	10	80
2PB2.7	in	6.38	4.8	3.15	0.3148 0.3149	0.94	0.79	0.63	1.77	0.39	7.48	8.27	0.39	3.15
10000	mm	210	170	128	8h5	-	20	16	45	10	190	210	10	80
4PB2.7	in	8.27	6.69	5.04	0.3148 0.3149	-	0.79	0.63	1.77	0.39	7.48	8.27	0.39	3.15
MODEL	units	Р	øQ	øR	S	Т	U	V	W	AA	Weig	ht		
	mm	100	10.5	6.4	90 ±0.1	220	81	152	7.6	48	~ 4.21	kg		
1PB-2.7	in	2.04	0.442	0.050	0.547	0.66	2.72	E 00	0.200	1.00	. 0.3	lh		

MODEL	units	Р	øQ	øR	S	Т	U	V	W	AA	Weight
	mm	100	10.5	6.4	90 ±0.1	220	81	152	7.6	48	~ 4.2 kg
1PB-2.7	in	3.94	0.413	0.252	0.547 0.539	8.66	2.72	5.98	0.299	1.89	~ 9.3 lb
	mm	100	10.5	6.4	90 ±0.1	220	69	152	7.6	48	~ 5.3 kg
2PB2.7	in	3.94	0.413	0.252	0.547 0.539	8.66	2.72	5.98	0.299	1.89	~ 11.7lb
100 c =	mm	100	10.5	6.4	90 ±0.1	220	45	152	7.6	48	~ 7.5 kg
4PB2.7	in	3.94	0.413	0.252	0.547 0.539	8.66	1.77	5.98	0.299	1.89	~ 16.6 lb

a) For calibration in  $N \cdot m$  with weight in kg



# PB 43 DIMENSIONS



CAUTION: All PB Series Dynamometers must be water cooled.

NOTE: Original dimensions are in Metric units. Dimensions converted to English units have been rounded up to 4 decimal places.

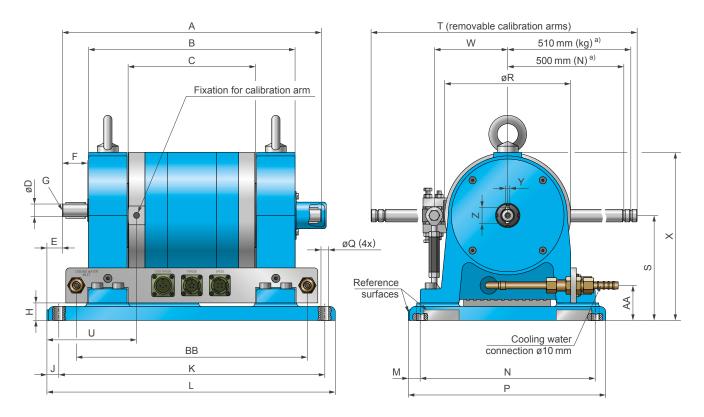
MODEL	units	Α	В	С	øD	E	F	G <sup>b)</sup>	Н	J	K	L	M	N	Р
	mm	240	186	100	12h6	22	25		25	22	240	284	22	160	202
1PB43	in	9.45	7.32	3.94	0.4724 0.4721	0.87	0.98		0.98	0.87	9.45	11.18	0.87	6.30	7.95
	mm	290	236	150	12h6	22	25	M4	25	22	290	334	22	160	202
2PB43	in	11.42	9.29	5.91	0.4724 0.4721	0.87	0.98		0.98	0.87	11.42	13.15	0.87	6.30	7.95
MODEL	units	øQ	øR	S	Т	U	W	X	Υ	Z	AA	ВВ	Wei	ight	
	mm	9	145	125 <sup>±0.05</sup>	524	153	80	198	4 h9	15	46	202	~ 24	4 kg	
1PB43															
	in	0.35	5.71	4.923 4.919	20.63	6.02	3.15	7.80	0.1574 0.1563	0.59	1.81	7.95	~ 5	3lb	
2PB43	in mm	0.35 9	5.71 145	4.923 4.919 125 ±0.05		6.02 167	3.15 80	7.80 198	0.1574 0.1563 4 h9	0.59 15	1.81 46	7.95 252	~ 5 ~ 3		

a) 255 mm for a calibration in N·m with weight in kg (use outer groove); 250 mm for calibration in N·m with weight in N (use inner groove)

b) Center according to DIN 332-D



# PB 65 DIMENSIONS



CAUTION: All PB Series Dynamometers must be water cooled.

NOTE: Original dimensions are in metric units. Dimensions converted to English units have been rounded up to 4 decimal places.

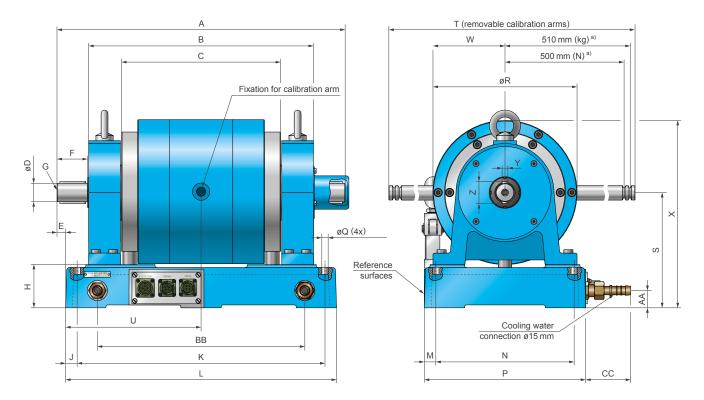
MODEL	units	Α	В	С	øD	Е	F	G <sup>b)</sup>	Н	J	K	L	M	N	Р
	mm	300	225	112	18h6	22	36		25	17	310	342	17	250	282
1PB65	in	11.81	8.86	4.41	0.7086 0.7083	0.87	1.42	.45	0.98	0.67	12.2	13.46	0.67	9.84	11.10
0.00.00	mm	370	295	182	18h6	22	36	M5	25	17	380	412	17	250	282
2PB65	in	14.57	11.61	7.17	0.7086 0.7083	0.87	1.42		0.98	0.67	14.96	16.22	0.67	9.84	11.10
MODEL	units	øQ	øR	S	T	U	W	X	Υ	Z	AA	ВВ	Weig	ght	
	mm	11	180	150±0.1	1034	128	105	240	6h9	23	50	260	~ 55	kg	
1PB65	in	0.43	7.09	5.909 5.902	40.71	5.04	4.13	9.45	0.2362 0.2351	0.91	1.97	10.24	~ 122	2lb	
0.00.00	mm	11	180	150 <sup>±0.1</sup>	1034	128	105	240	6h9	23	50	330	~ 70	kg	
2PB65	in	0.43	7.09	5.909 5.902	40.71	5.04	4.13	9.45	0.2362 0.2351	0.91	1.97	12.99	~ 15	5lb	

a) 510 mm for a calibration in N·m with weight in kg (use outer groove); 500 mm for a calibration in N·m with weight in N (use inner groove).

b) Center according to DIN 332-D



# PB 115 DIMENSIONS



**CAUTION**: All PB Series Dynamometers must be water cooled.

NOTE: Original dimensions are in metric units. Dimensions converted to imperial units have been rounded up to 4 decimal places.

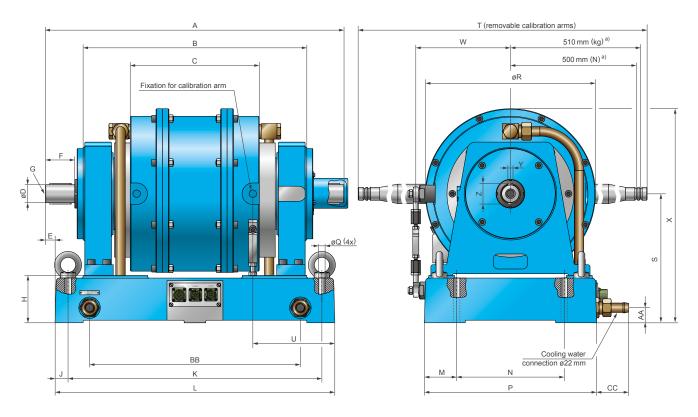
MODEL	units	Α	В	С	øD	Е	F	G <sup>b)</sup>	Н	J	K	L	M	N	Р
	mm	390	280	166	32h6	-40	54		75	20	430	470	40	200	280
1 PB 115	in	15.35	11.02	6.54	1.2598 1.2593	-1.57	2.13	140	2.95	0.79	16.93	18.50	1.57	7.87	11.02
	mm	500	390	276	32h6	15	54	M8	75	20	430	470	40	200	280
2 PB 115	in	19.69	15.35	10.87	1.2598 1.2593	0.59	2.13		2.95	0.79	16.93	18.50	1.57	7.87	11.02
MODEL	units	øQ	øR	S	Т	U	W	X	Υ	Z	AA	ВВ	CC	Weig	ght
	mm	11	250	200±0.1	1038	197	125	325	10h9	38	30	360	80	~	80 kg
1 PB 115															
	in	0.43	9.84	7.878 7.870	40.87	7.76	4.92	12.80	0.3937 0.3932	1.50	1.18	14.17	3.15	~ ^	177 lb
2PB115	in mm	0.43	9.84 250	7.878 7.870 200±0.1	40.87 1038	7.76 235	4.92 125	12.80 325	0.3937 0.3932 10 h9	1.50 38	1.18	14.17 360	3.15 80		177 lb 30 kg

a) 510 mm for a calibration in N·m with weight in kg (use outer groove); 500 mm for a calibration in N·m with weight in N (use inner groove).

b) Center according to DIN 332-D



# **PB15 DIMENSIONS**



**CAUTION**: All PB Series Dynamometers must be water cooled.

NOTE: Original dimensions are in metric units. Dimensions converted to imperial units have been rounded up to 4 decimal places.

MODEL	units	Α	В	С	øD	Е	F	G <sup>b)</sup>	Н	J	K	L	M	N	Р
	mm	544	370	150	42g6	-53	68		110	30	590	650	75	250	400
1PB15	in	21.42	14.57	5.91	1.6531 1.6526	-2.09	2.68		4.33	1.18	23.23	25.59	2.95	9.84	15.75
0.00.45	mm	694	520	300	42g6	22	68		110	30	590	650	75	250	400
2PB15	in	27.32	20.47	11.81	1.6531 1.6526	0.87	2.68	M8	4.33	1.18	23.23	25.59	2.95	9.84	15.75
	mm	994	820	600	42g6	-3	68		110	30	940	1000	75	250	400
4 PB 15	in	39.13	32.28	23.62	1.6531 1.6526	-0.12	2.68		4.33	1.18	37.01	39.37	2.95	9.84	15.75
MODEL	units	øQ	øR	S	T	U	W	Χ	Υ	Z	AA	ВВ	CC	Weig	ıht
15515	mm	15	395	300 <sup>±0.2</sup>	1030	265	220	498	12 h9	48	35	490	75	~ 18	
1PB15	mm in	15 0.59	395 15.55	300 <sup>±0.2</sup> 11.819 11.803	1030 40.55	265 10.43	220 8.66	498 19.61	12 h9 0.471 0.472	48 1.89	35 1.38		75 2.95	~ 18	
												490		~ 18	5 kg 08 lb
1 PB 15 2 PB 15	in	0.59	15.55	11.819 11.803	40.55	10.43	8.66	19.61	0.471 0.472	1.89	1.38	490 19.29	2.95	~ 18 ~ 40 ~ 29	5 kg 08 lb
	in mm	0.59	15.55 395	11.819 11.803 300 <sup>±0.2</sup>	40.55 1030	10.43 190	8.66 220	19.61 498	0.471 0.472 12 h9	1.89	1.38	490 19.29 490	2.95 75	~ 18 ~ 40 ~ 29	5 kg 08 lb 0 kg 40 lb

a) 510 mm for a calibration in N·m with weight in kg (use outer groove); 500 mm for a calibration in N·m with weight in N (use inner groove).

NOTE: 3D STEP files of most of our products are available on our website: www.magtrol.com; other files are available on request.

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b) Center according to DIN 332-D



### **RELATED PRODUCTS**

#### **WBSERIES - EDDY-CURRENT DYNAMOMETER**



Fig. 3: 1WB43 | Eddy-Current Dynamometer

Eddy-Current Brake D y n a m o m e t e r s WB Series are ideal for applications requiring high speeds and also when operating in the middle to high power range. Eddy-Current Brakes provide increasing torque as the speed increases,

reaching peak torque at rated speed. The dynamometers have low inertia as a result of small rotor diameter. Brake cooling is provided by a water circulation system, which passes inside the stator to dissipate heat generated by the braking power. The water cooling in the WB provides high continuous power ratings (max. 140 kW).

#### TANDEM SERIES - WB + PB DYNAMOMETER



Fig. 4: 4WB 15 + 4PB 15 | TANDEM

Because the characteristics of the WB and PB dynamometers are complementary, Magtrol is able to offer them mounted in a tandem setup. Each dynamometer (WB and PB) can autonomously operate according to its own characteristics. An electromagnetic clutch is needed for this application which automatically switches off at the maximum speed of the PB Powder Dynamometer and automatically switches on at zero speed.

#### **DUAL SERIES - DOUBLE WB DYNAMOMETER IN TANDEM SETUP**

For application requiring higher power in a dedicated speed range, Magtrol offers some of the Eddy Current Dynamometer mounted in line on a common base. This would be for example the models 2WB65+2WB65 (rated torque 40N·m, max speed 24000 rpm, max power 24kW) or 2WB115+2WB115 (rated torque 200N·m, max speed 15000 rpm, max power 60kW).

#### DYNAMOMETER OPTIONS \_

#### SPEED ENCODER (DG)

PB Series Dynamometers, are equipped with a encoder (optical speed sensor) 30 PPR (PB 2.7& PB 43) or 60 PPR (PB 65, PB 115 & PB 15) encoder.

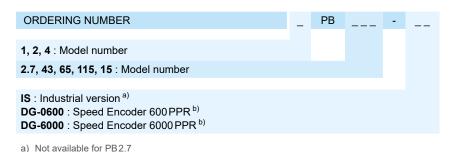
On PB Dynamometers, a  $600\,\text{PPR}$  or  $6\,000\,\text{PPR}$  encoder is available as an option for low speed applications.

# INDUSTRIAL VERSION (IS)

PB Series Dynamometers are also available in an industrial version (excepte PB 2.7), which includes the base plate, but does not provide torque nor speed measurement.

**NOTE:** Dimensions of the specific versions can slightly vary from the standard versions. Please, contact our sales technicians for specific drawing.

#### ORDERING INFORMATION



Examples:

2 PB 43 Powder Dynamometer, Industrial version would be ordered as: **2PB43-IS** 

4 PB 115 Powder Dynamometer, with speed pickup 600 PPR would be ordered as: **4PB115-DG0600** 

1 PB 2.7 Powder Dynamometer would be ordered as: 1PB2.7

b) PPR means Pulses Per Revolution



#### SYSTEM OPTIONS AND ACCESSORIES \_

# DSP 7000 - HIGH-SPEED PROGRAMMABLE **DYNAMOMETER CONTROLLERS**

Magtrol's Model DSP 7000 High Speed Programmable Dynamometer Controller employs state-of-the-art Digital Signal Processing Technology to provide superior motor testing capabilities. Designed for use with any Magtrol Hysteresis, Eddy-Current or Powder Dynamometer, Magtrol In-Line Torque Transducer or auxiliary instrumentation, the DSP 7000 can provide complete PC control via the USB or optional IEEE-488 or RS-232 interface. With up to 500 readings per second, the DSP7000 is ideally suited for both the test lab and the production line.



Fig. 5: DSP 7001 | Programmable Dynamometer Controllers

#### TSC 401 - TORQUE/SPEED CONDITIONER

The TSC 401 is the Torque/Speed Conditioner used to connect Magtrol Eddy-Current (WB Series) or Powder (PB Series) Dynamometers to the DSP7000 Controller. Powered by the DSP7000, and based on a precision instrumentation amplifier, the unit amplifies and filters the torque signal. It also provides power supply and connections for the speed pickup sensor which is located in the dynamometer.

#### **DES SERIES - POWER SUPPLIES**

DES Series Power Supplies are specially designed for the full range of Magtrol's Eddy-current and Powder brake dynamometers with the design goal providing the best response time. The DES Series supplies are packaged in an industrial housing made of cast aluminum. This housing must be installed directly on the test bench, ideally on a thermal conductive surface.



Fig. 6: Custom Motor Test System with WB brake

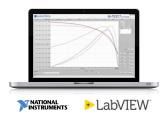
#### **MODEL 7500 - POWER ANALYZERS**

The Magtrol MODEL7500 Power Analyzer is an easy-to-use instrument ideal for numerous power measurement applications. From DC to 80 kHzAC, the MODEL 7500 Series measures volts, amps, watts, volt-amps, frequency, crest factor, Vpeak, Apeak and power factor in one convenient display. They may be used either as stand-alone instruments or in conjunction with any Magtrol Hysteresis, Eddy-Current or Powder Brake Dynamometer; any Magtrol Dynamometer Controller and M-TEST Software for more demanding motor test applications.



Fig. 7: MODEL 7500 | Power Analyzers

#### M-TEST - MOTOR TESTING SOFTWARE



Magtrol M-TEST is an advanced motor testing software (Windows® based) for data acquisition. Used with a Magtrol Programmable Dynamometer Controller (e.g. DSP7000), M-TEST works with any Magtrol

Dynamometer or In-Line Torque Transducer to help determine the performance characteristics of a motor under test. Up to 63 parameters are calculated and displayed utilizing M-TEST's feature-rich testing and graphing capabilities.

An integral component of any Magtrol Motor Test System, M-TEST performs ramp, curve, manual, pass/fail, coast and overload to trip tests in a manner best suited to the overall efficiency of the test rig. Written in LabVIEW™, M-TEST has the flexibility to test a variety of motors in a multitude of configurations. The data generated from this user-friendly program can be stored, displayed and printed in tabular or graphical formats, and is easily imported into a spreadsheet.

Magtrol can also make custom modifications to the software to meet additional motor testing requirements.

#### **CMTS - CUSTOM MOTOR TEST SYSTEMS**

MAGTROL provides motor testing components to turnkey solutions for all your motor testing needs. Typical test benches include: dynamometers, 4-quadrant loading motors, tables, fixtures, control racks, power supplies, power analyzers, ohmmeters, temperature measurment and dedicated M-TEST software. Other sensors can be integrated upon request.

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