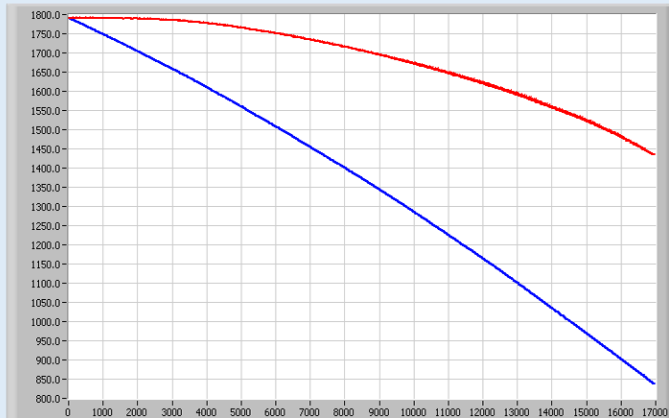
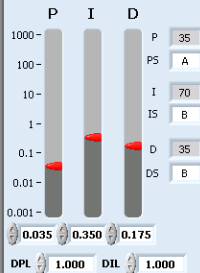


Speed Control Mode Adjust PID



Actual 
Ideal 



Save Setup

Run